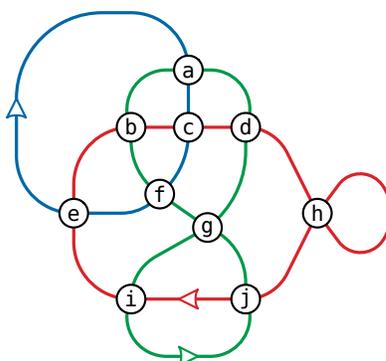


These questions are rather long, so I don't expect everyone to submit solution to everything.

- Let  $\Gamma = \{\gamma_1, \gamma_2, \dots, \gamma_k\}$  be a set of generic closed curves that intersect each other only pairwise, transversely, and away from their vertices; we call any such set a (*generic*) *family of planar curves*. For simplicity, assume that every curve  $\gamma_i$  is either non-simple or intersects another curve  $\gamma_j$ . Then the image of  $\Gamma$  is a 4-regular plane graph, which may be disconnected. Conversely, every 4-regular plane graph is the image of a family of planar curves.

A *Gauss paragraph* of  $\Gamma$  is a family of  $k$  strings, obtained by uniquely labeling the vertices of  $\Gamma$ , and then listing the vertices in order along each curve  $\gamma_i$  in an arbitrary direction, starting at an arbitrary basepoint, considering the curves in arbitrary order.



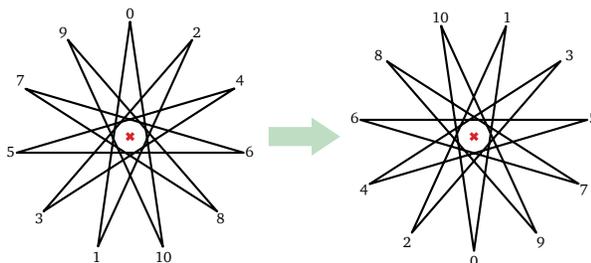
A connected family of planar curves with Gauss paragraph  $\{acfe, jgfbadgi, iebcdhhj\}$ .

Now let's go the other direction. A Gauss paragraph is any set of non-empty strings in which any symbol appears exactly twice or not at all. Each Gauss paragraph  $X$  defines a 4-regular graph  $G(X)$  whose vertices are the characters in  $X$  and whose edges correspond to adjacent character pairs. If  $X$  is the Gauss paragraph of a family of planar curves, then  $G(X)$  is the image graph of that family.

- Prove that if  $X$  is the Gauss paragraph of a family of planar curves, then the edges of  $G(X)$  can be directed so that every vertex has in-degree 2 and out-degree 2. [*Hint: Consider self-intersection points of one curve and intersection points of two curves separately.*]
- Describe a linear-time algorithm that either directs the edges of  $G(X)$  as described in part (a) or correctly reports that no such orientation exists, given the Gauss paragraph  $X$  as input.
- Prove that  $X$  is the Gauss paragraph of a generic family of planar curves if and only if  $G(X)$  has a planar embedding such that every component has a weakly simple Euler tour.
- Sketch a linear-time algorithm to decide whether a given string is the Gauss paragraph of a generic family of planar curves. (Just describe the necessary modifications to the algorithm for single curves.)

2. Fix an arbitrary point  $o$  in the plane, called the *origin*. Let  $P$  be a polygon in  $\mathbb{R}^2 \setminus o$  with vertices  $p_0, p_1, \dots, p_{n-1}$ . A *vertex move* on  $P$  replaces an arbitrary vertex  $p_i$  with a new point  $q_i$ . This vertex move is *safe* if neither of the triangles  $\Delta p_i q_i p_{i-1}$  and  $\Delta p_i q_i p_{i+1}$  contains  $o$ . (All index arithmetic is modulo  $n$ .) Every sequence of safe vertex moves describes a homotopy between two polygons with the same number of vertices and the same winding number around the origin.

(a) Let  $n$  be an arbitrary odd integer. Let  $P$  be a regular star polygon with  $n$  vertices spaced evenly around the unit circle, such that  $wind(P, o) = \lfloor n/2 \rfloor$ , as shown below. Describe how to rotate  $P$  around the origin by half a circle using  $O(n)$  safe triangle moves.

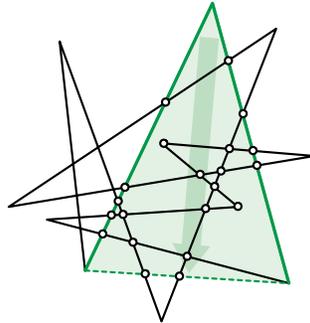


This rotation can be performed with  $O(n)$  safe triangle moves.

(b) Let  $P$  and  $Q$  be two arbitrary  $n$ -gons in  $\mathbb{R}^2 \setminus \{o\}$ , such that  $wind(P, o) = wind(Q, o)$ . Prove that  $P$  can be transformed into  $Q$  using  $O(n)$  safe vertex moves. [Hint: Aim for a canonical polygon with winding number  $wind(P, o)$ . The star polygon in part (a) may not be the best candidate.]

3. Let  $P$  be an arbitrary polygon with  $n$  vertices; for simplicity, assume no three vertices in  $P$  are collinear. The *image graph*  $G(P)$  is a planar straight-line graph whose nodes are the vertices of  $P$  and the intersection points of edges of  $P$ . Let  $N$  denote the number of nodes in the image graph  $G(P)$ . Trivially,  $n \leq N \leq \binom{n}{2}$ .

We can easily reduce  $P$  to a triangle by repeatedly replacing two successive edges  $p_{i-1}p_i$  and  $p_i p_{i+1}$  with a new edge  $p_{i-1}p_{i+1}$ , deleting the shared vertex  $p_i$ . Define the *cost* of deleting vertex  $p_i$  to be the number of nodes of  $G(P)$  that lie in the triangle  $\Delta p_{i-1}p_i p_{i+1}$ , except for the three vertices  $p_{i-1}$ ,  $p_i$ , and  $p_{i+1}$ . For example, if  $P$  is convex, every vertex deletion has cost zero.



A vertex move with cost 22.

- (a) Prove that any vertex deletion with cost  $k$  can be transformed into a sequence of  $O(k)$  homotopy moves ( $1 \leftrightarrow 0$ ,  $2 \leftrightarrow 0$ , and  $3 \rightarrow 3$ ), by treating the polygon as a generic curve. [Hint: Watch out for spurs!] This is the motivation for my definition of cost.
- (b) Trivially, every vertex deletion has cost  $O(n^2)$ , and therefore any sequence of  $n - 3$  vertex deletions has total cost  $O(n^3)$ . Prove that this  $O(n^3)$  bound is tight in the worst case. [Hint: See problem 2.]
- (c) Prove that if  $P$  is simple, there is a sequence of  $n - 3$  vertex deletions with total cost 0.
- (d) Prove that any polygon  $P$  can be reduced to a triangle by a sequence of  $n - 3$  vertex deletions with cost  $O(N^2)$ . [Hint: A vertex deletion can actually increase  $N$ .]
- ★(e) Prove or disprove: There is a sequence of  $n - 3$  vertex deletions with total cost  $O(N^{3/2})$ . Your proof of part (b) implies a worst-case  $\Omega(N^{3/2})$  lower bound.